# On the in-the-middle algorithm and heuristic and some of its properties

Dag Wedelin, Data Science Division, CSE, Chalmers

Beginning with special cases of linear programming, I will describe these algorithms, and some of their properties. I will also briefly discuss the max-sum problem and related algorithms, and discuss some of the general challenges with numerical propagation algorithms in relation to classical constraint programming.





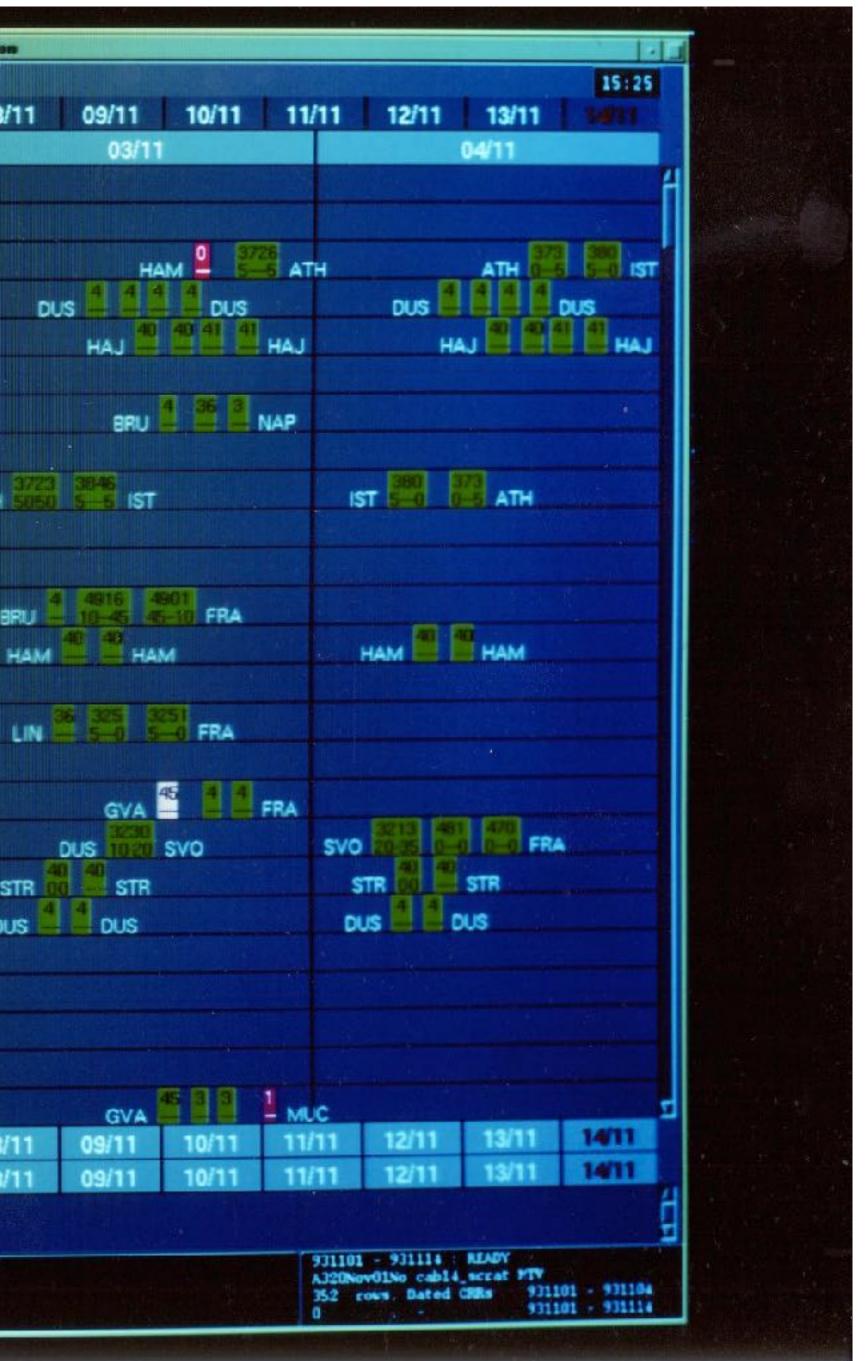
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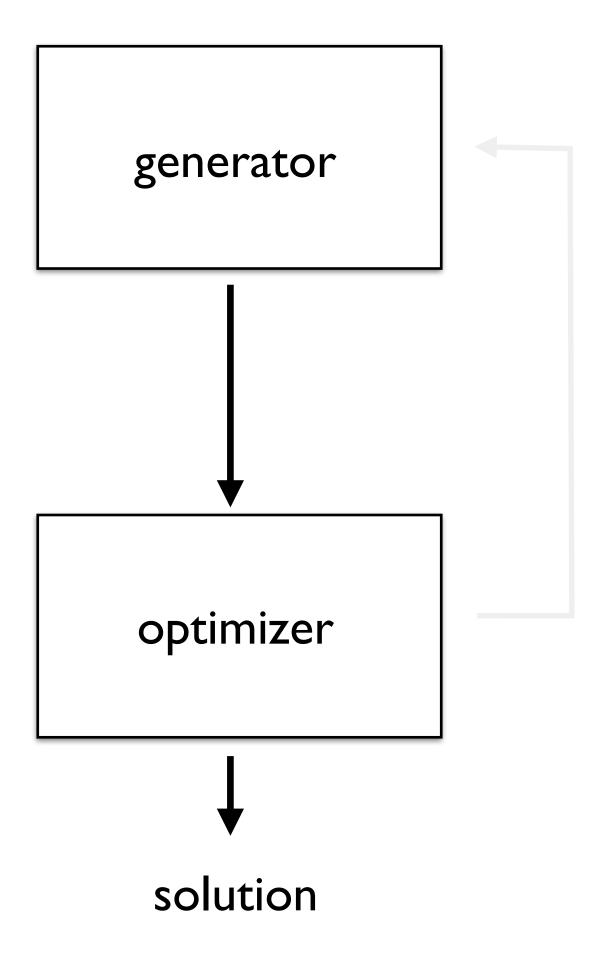
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## In crew pariring system

generate many legal pairings

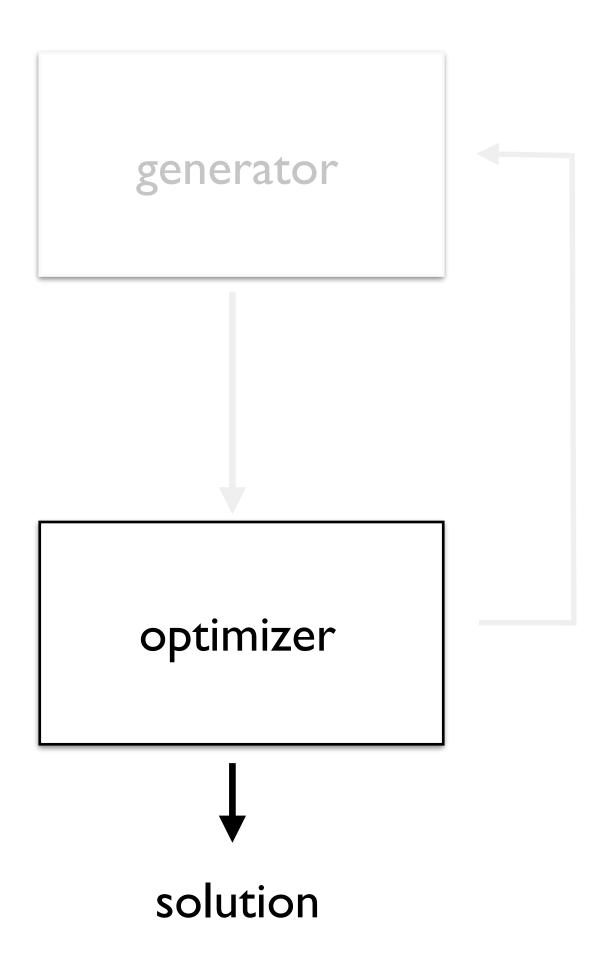
select an optimal subset of these pairings



## In crew pariring system

#### min cx $Ax \ge 1$ (set covering) $Cx \le d$ (base capacity)

x binary vector



## paqs optimizer

#### • in-the-middle algorithm

#### • in-the-middle heuristic

Regularly benchmarked, continuously improved.

In production since many years.

Parallel implementation

the in-the-middle algorithm

## The simple assignment problem

tasks



6 8 10 5

max C, X, + C, X, + ... + C, K, K, K

Subject to

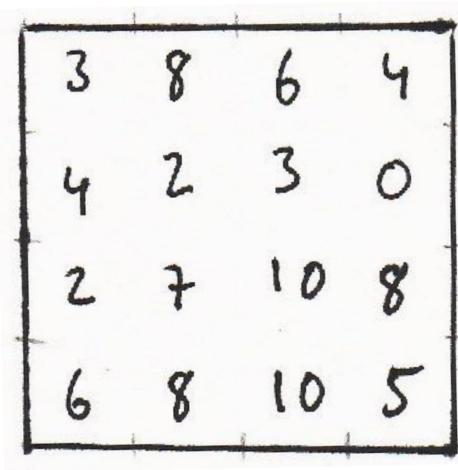
 $\begin{cases} X_1 + X_5 + X_9 + X_{13} = 1 \\ \vdots \\ \vdots \\ \vdots \end{cases}$ 

30, 

2 3 0 

 $\Rightarrow$ ...

Subtract average of largest and second largest numbers.



Iterate for all rows and columns until there are no more sign changes.



Simplest possible algorithm? (just subtracting the smallest number does not work)

## select assignments with positive cost!

# In-the-middle for 0-1 ILP Max CX Ax=b X binary

A contains  $\{-1,0,1\}$ b integer inequalities ok

Consider

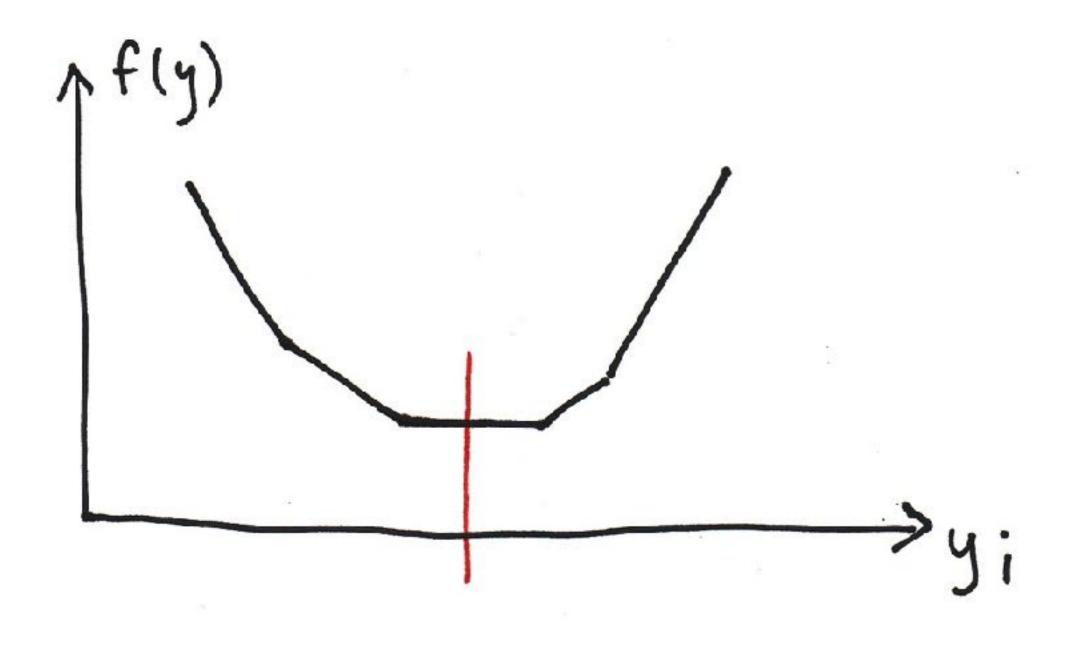
interval

C = C - yA

#### iteratively make single constraints feasible by selecting the dual yi <u>in-the-middle</u> of the possible

## A "dual" algorithm

Minimize piecewise linear convex function with coordinate descent



## $\min_{y} f(y) = yb + \max_{0 \le x \le 1} \bar{c}x$

#### Theorem:

The in-the-middle algorithm can only solve "easy" ILP problems (the LP relaxation has a unique solution that is integer).

What about convergence?

# How does in-the-middle fail for difficult ILP's?

#### a lot of zeros...

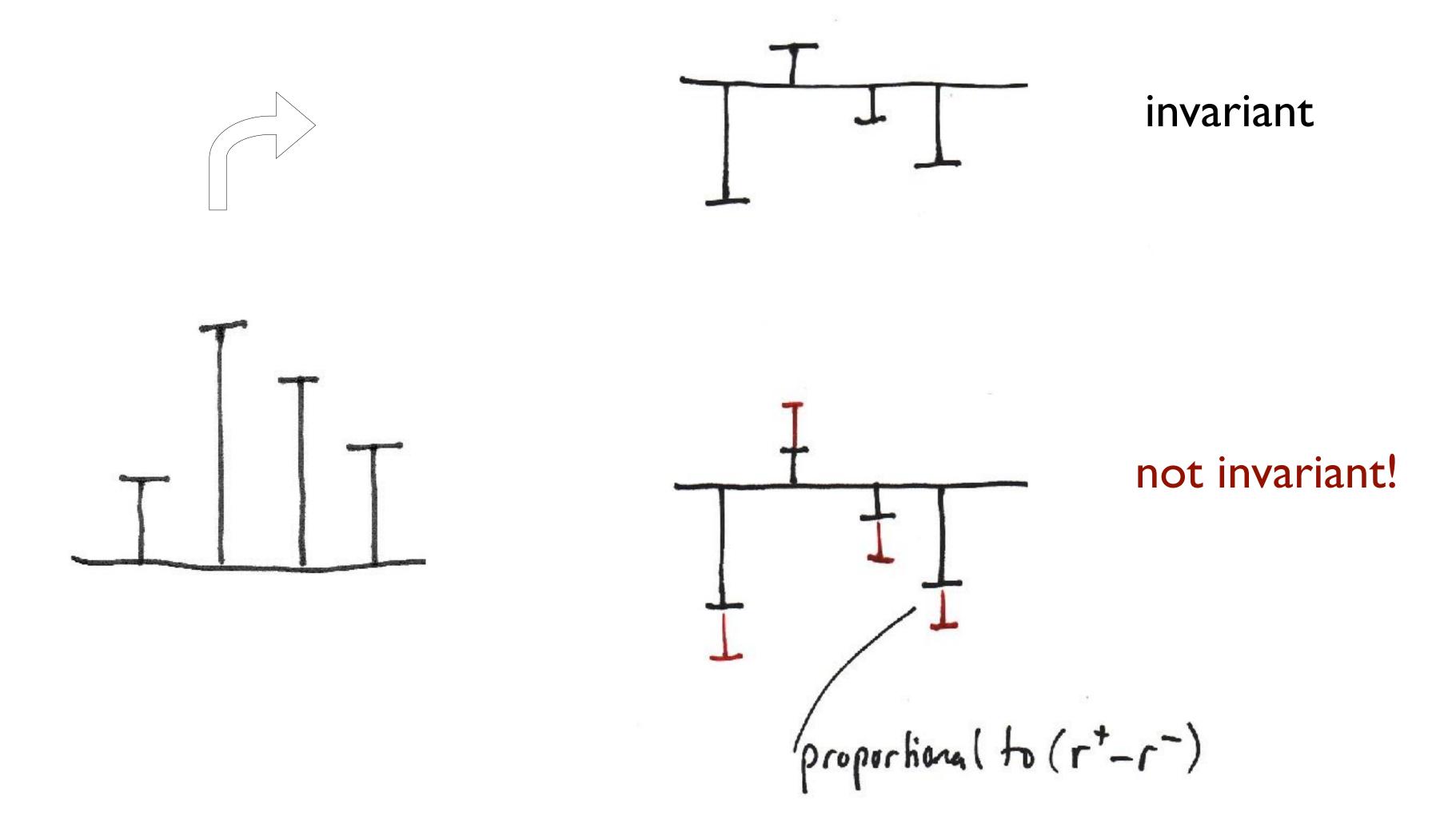
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eg. 8-queens with diagenal constraints

#### A small difficult problem

max X1+X2+X2  $X_1 = X_2 + X_3$  $X_2 = X_1 + X_3$  $X_3 = X_1 + X_3$  $\overline{c}_1 = \overline{c}_2 = \overline{c}_2 = 0$  is a fixpoint!

#### in-the-middle <u>heuristic</u> for difficult 0-1 ILP's

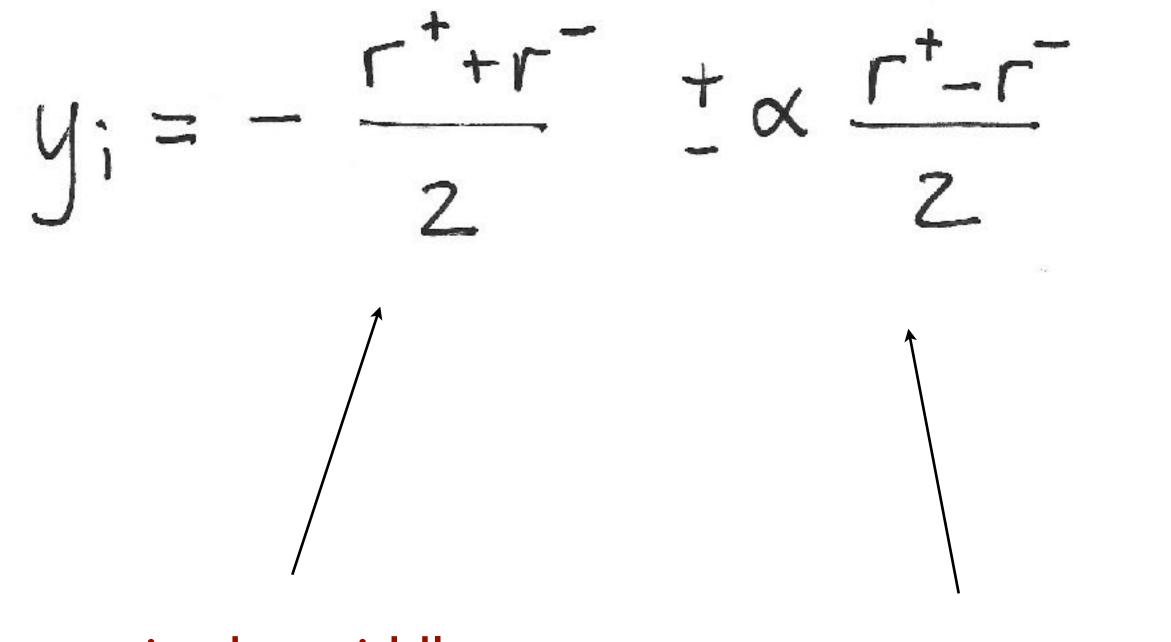


# Now it suddenly works!

(weighted 8-queens problem)

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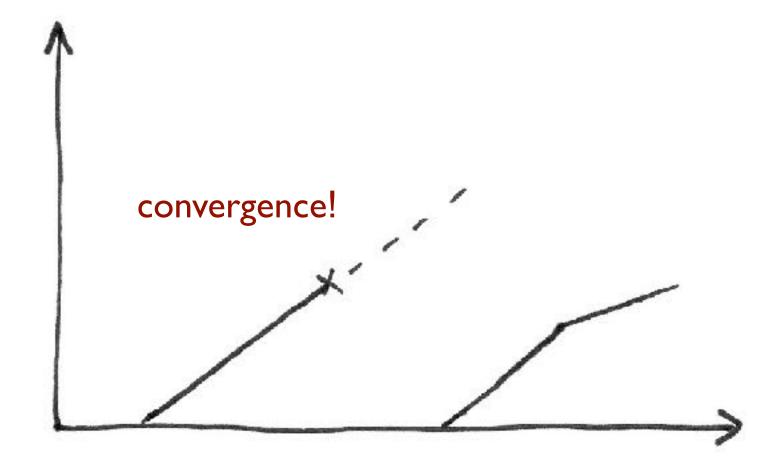
#### in-the-middle heuristic



in-the-middle algorithm

#### in-the-middle heuristic

#### Sweep mechanism



(also small random costs for resolving ties)

## best results with as low disturbance as possible

the max-sum problem

#### The max-sum problem

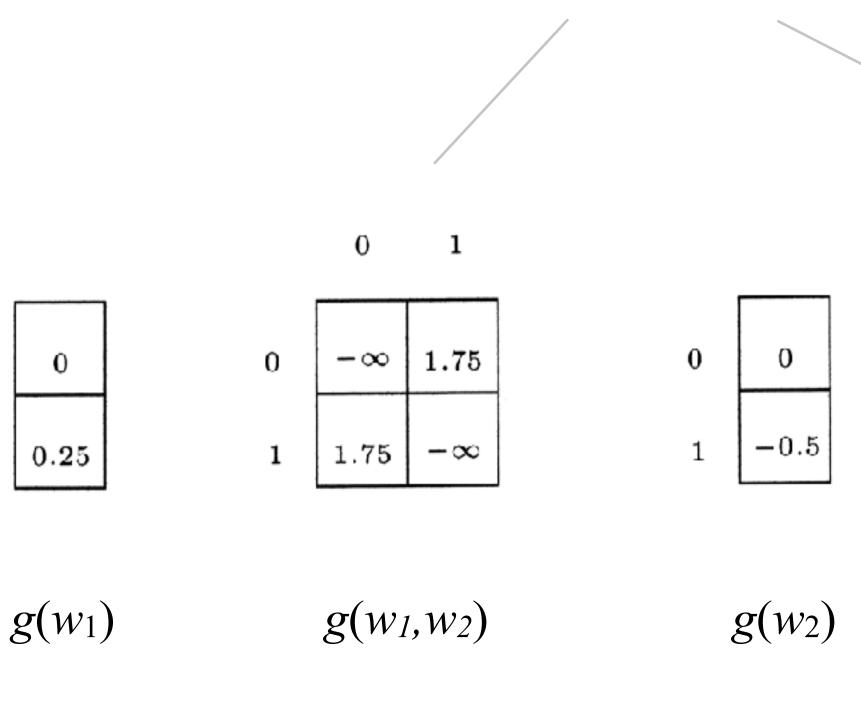
vector of discrete variables

#### $\max_{w} f(w) = \sum g_k(w^k) + C$ wk

Allows a highly non-linear cost function

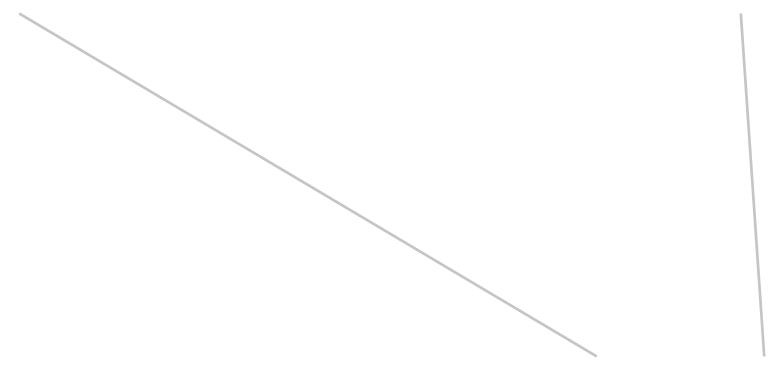
#### different subsets of the variables

#### constraint components

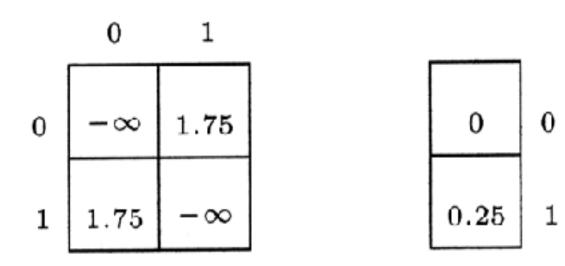


0

1



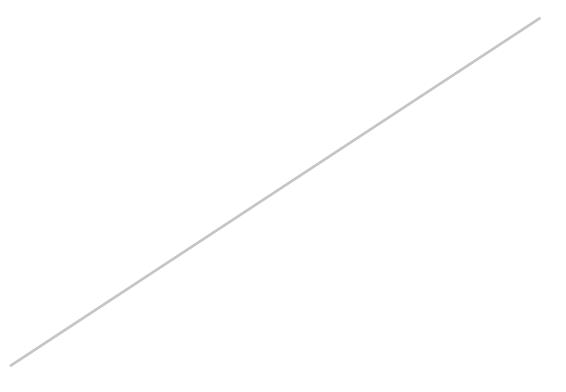
variable components



$$g(w_2,w_3)$$

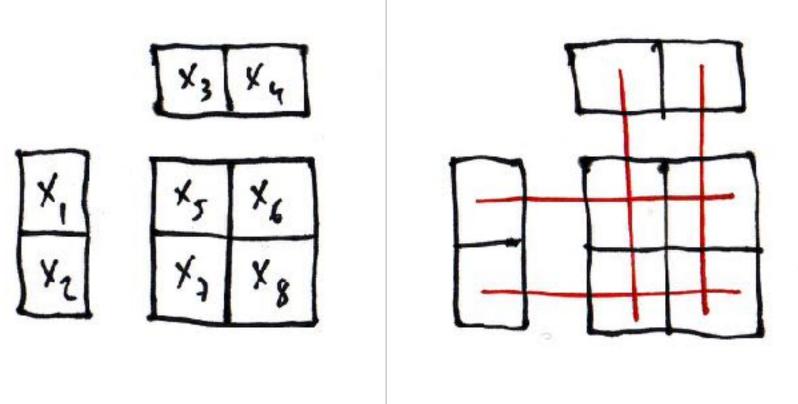
 $g(w_3)$ 

0



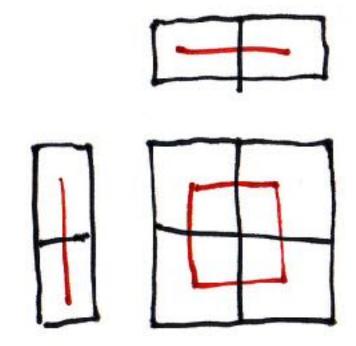
modelling and solving the max-sum problem as an ILP

#### The max-sum ILP



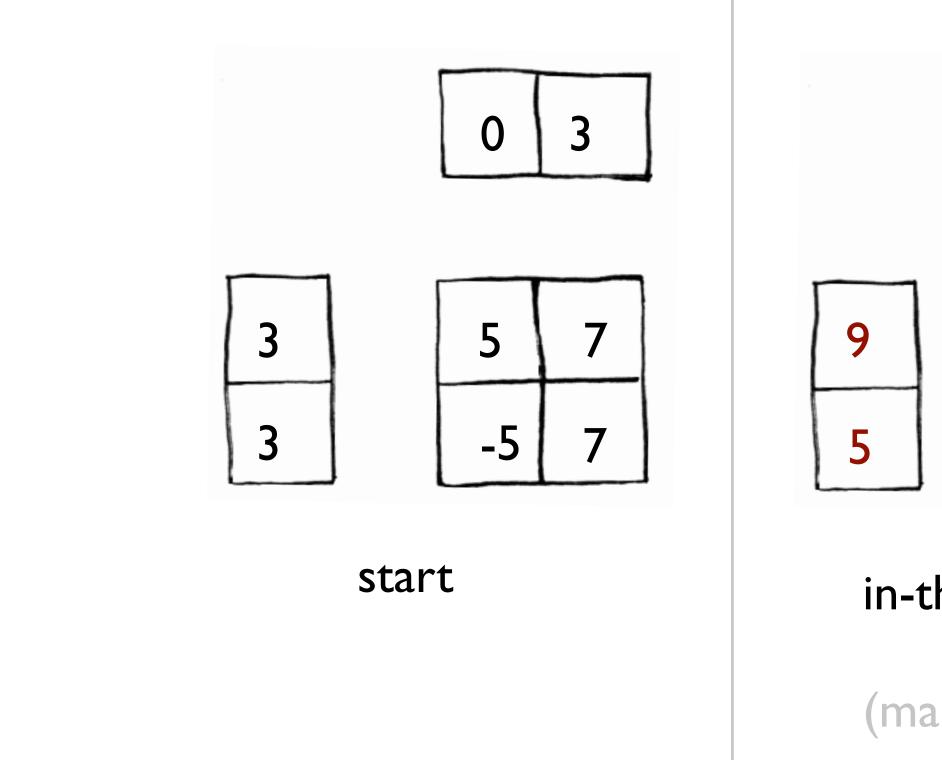
marginalization constraints

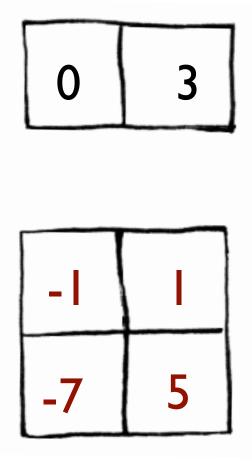
For C, we introduce an extra variable  $x_c$ , together with the constraint  $x_c = 1$ .



normalization constraints

#### Max-sum with the in-the-middle algorithm

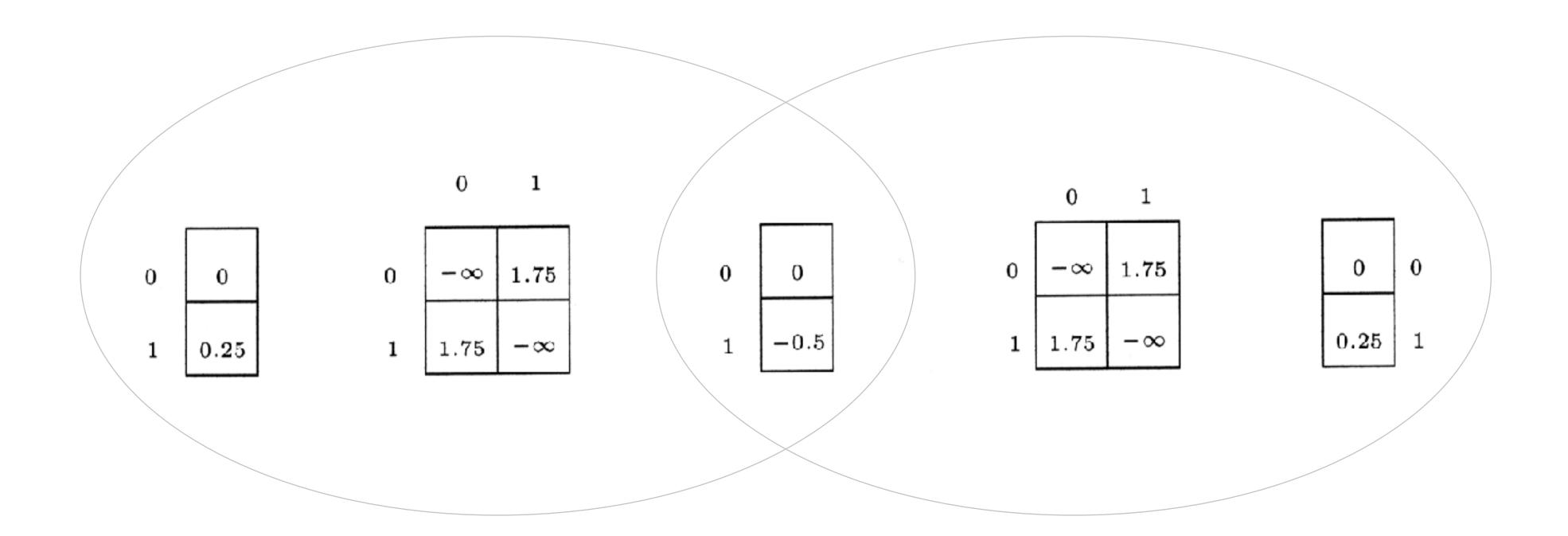




#### in-the-middle

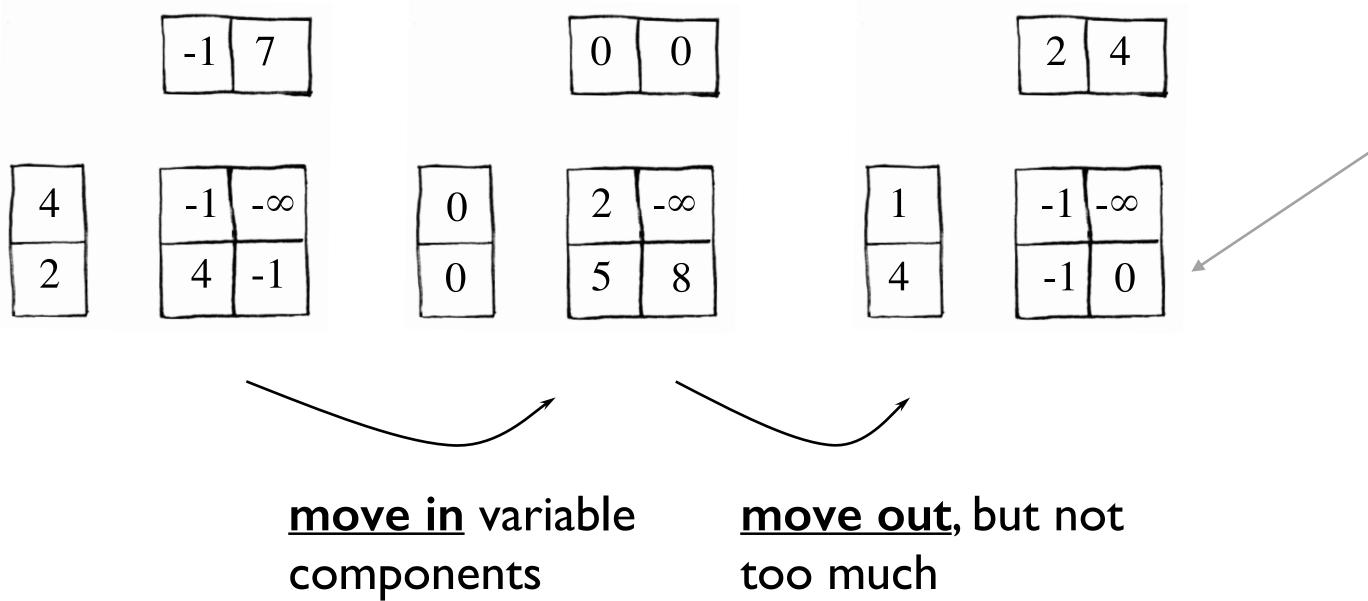
(makes linear constraint feasible)

#### Or solve entire subproblems with specialised algorithm!



#### Iteratively update one subproblem at a time

Move in and move out...

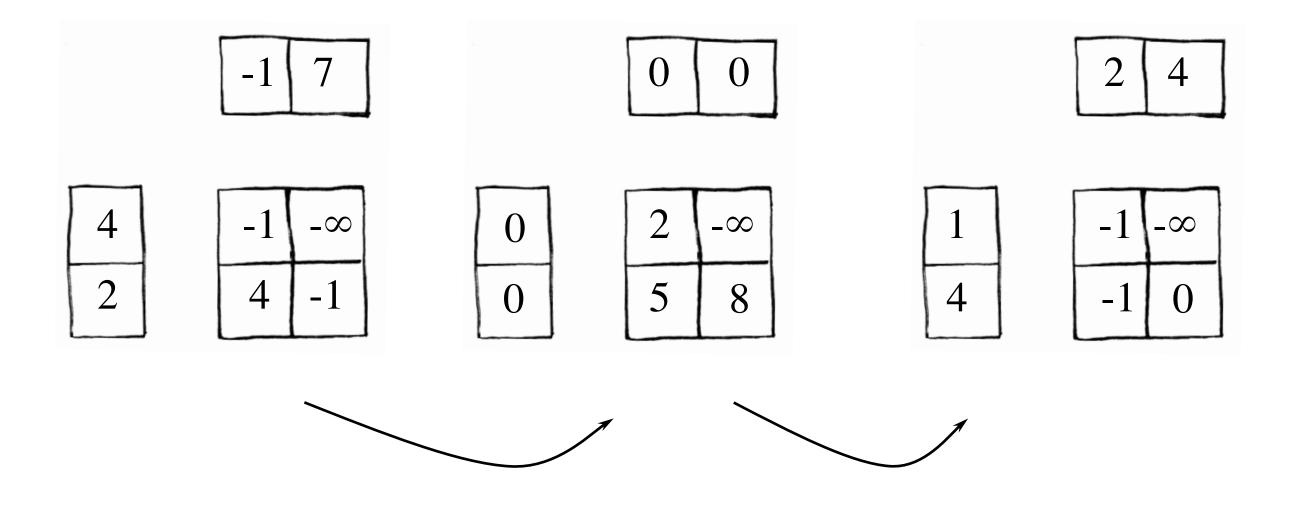


We want to keep the best combination still largest in constraint!

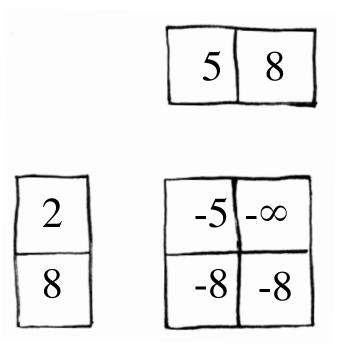
"non-conflicting"

minimizes f(y)

#### What if we move out "too much"?



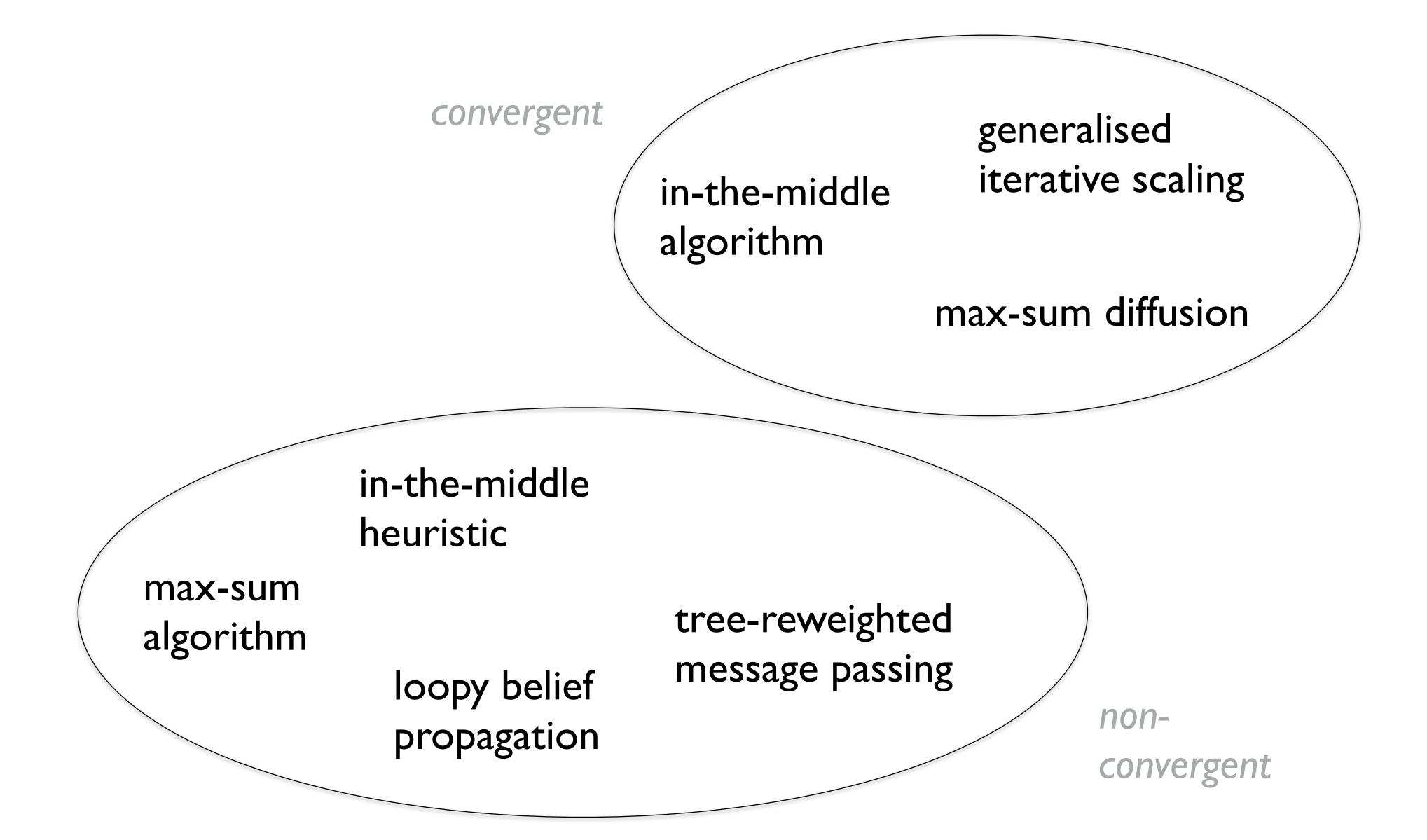
We can easily explain why the <u>max-sum</u> <u>algorithm</u> does not guarantee optimality!



here we have moved out even more, we get a "conflict"!

(max-sum algorithm!)

#### Many interesting relationships between algorithms!





#### Can we unify the models?

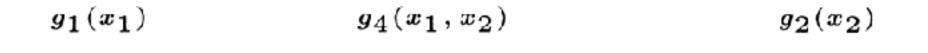
$$\max_{w} f(w) = \sum_{k} g_k(w^k) + C$$

# $\max cx$ Ax = b $x_j \in \{0, 1\}$

#### Let's model the other way around: ILP to max-sum!

 $\max\{2x_1 + 3x_2 + 2x_3 \mid x_1 + x_2 = 1, x_2 + x_3 = 1, x_j \text{ binary}\}.$ 

max  $g_1(x_1) + g_2(x_2) + g_3(x_3) + g_4(x_1, x_2) + g_5(x_2, x_3).$ 



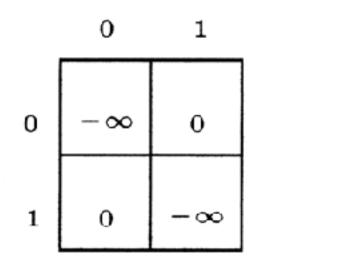
 $-\infty$ 

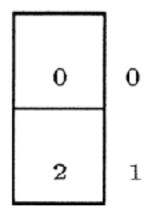
 $-\infty$ 

 $\mathbf{2}$ 

 $g_5(x_2, x_3)$ 

 $g_{3}(x_{3})$ 





 $\max_{w} f(w) = \sum_{k} g_k(w^k) + C$ 

if we move out as much as possible but not too much...

max-sum algorithm

The distinction between an ILP model and a max-sum model is blurred!

The in-the-middle updates can be seen as fast specialized max-sum constraint updates!

 $\max cx$ 

# Ax = b $x_j \in \{0, 1\}$

same as in-themiddle algorithm for the original ILP

 $\Rightarrow$ 

 $\Rightarrow$ 

same as in-themiddle heuristic (for  $\alpha = 1$ )

#### To note from a constraint programming perspective

Numerical propagation can solve many non-trivial problems with propagation only!

(no combinatorial search!)

#### Summary

## in-the-middle algorithm in-the-middle heuristic

unify models! unify algorithms!

END